

# Algorithmic Geometry      solution sketches - intersection of 2 circles

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*Subproblem: How many intersection*

# numIntPts

Draw examples

Decision logic

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1

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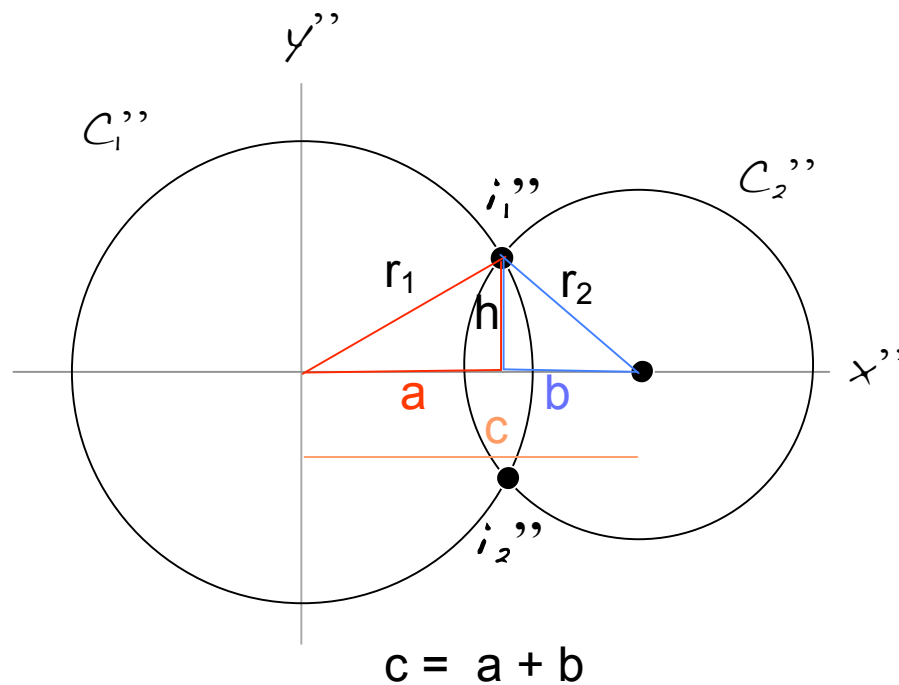
0

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2

*Subproblem: Locations of intersection*

Easier-to-solve special case:



$$a^2 + h^2 = r_1^2$$

$$b^2 + h^2 = r_2^2$$

$$a^2 - b^2 = r_1^2 - r_2^2$$

$$(a + b)(a - b) = r_1^2 - r_2^2$$

$$c(a - b) = r_1^2 - r_2^2$$

$$a - b = (r_1^2 - r_2^2) / c$$

$$a + b = c$$

$$2a = c + (r_1^2 - r_2^2) / c$$

$$2a = c^2/c + (r_1^2 - r_2^2) / c$$

$$a = (c^2 + r_1^2 - r_2^2) / 2c$$

$$c = C_2'' \cdot c \cdot x$$

$$a = (c^2 + r_1^2 - r_2^2) / 2c$$

$$h = \text{sqrt}(r_1^2 - a^2)$$

$$i_1'' = [ a \quad h ]$$

$$i_2'' = [ a \quad -h ]$$

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//***** Number of Intersection Points Of 2 Circles *****
// a HELPER function for intersectionPtsOf(C1, C2)
private static int numIntersectionPts(Circle C1, Circle C2) {
    if (identical(C1, C2)) return 3;
    if (Vec2.distance(C1.c, C2.c) == C1.r + C2.r) return 1;
    if (Vec2.distance(C1.c, C2.c) > C1.r + C2.r) return 0;
    if (Vec2.distance(C1.c, C2.c) == Math.abs(C1.r - C2.r)) return 1;
    if (Vec2.distance(C1.c, C2.c) < Math.abs(C1.r - C2.r)) return 0;
    return 2; // default if not 0, 1 or 3
}

//***** intersection Points Of 2 Circles *****
public static int intersectionPtsOf (Circle C1, Circle C2, /*returns*/ Vec2 i1, Vec2 i2) {
    int numPts = numIntersectionPts(C1, C2);
    if (numPts == 0 || numPts == 3) return numPts; // no intersection points can be computed

    // transform problem into simpler special case
    Circle C2_p = Circle.translate(C1.c, C2); // shift to C1-local coordinates
    DirVec newXaxis = new DirVec(C2_p.c);
    Circle C2_pp = Circle.rotate(newXaxis, C2_p); // rotate: centers C2_pp on positive x-axis

    double c = C2_pp.c.x;
    double a = ( c*c + C1.r*C1.r - C2.r*C2.r ) / (2*c);
    double h = Math.sqrt(C1.r*C1.r - a*a);
    Vec2 i1_pp = new Vec2(a,h);
    Vec2 i2_pp = new Vec2(a,-h);

    // back-transform using Unrotate then Untranslate
    i1.copyFrom(Vec2.untranslate(C1.c, Vec2.unrotate(newXaxis,i1_pp)));
    i2.copyFrom(Vec2.untranslate(C1.c, Vec2.unrotate(newXaxis,i2_pp)));
    return numPts;
}

```

